

Graphic user interface for synchrotron beamline *Interfaz gráfica de usuario para una línea de luz de sincrotrón*

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Abstract: This research consisted of developing a graphical user interface in Python language for the reconstruction of images based on the propagation technique (PBI). The methodology used consisted of rewriting and ordering the existing code by reformulating it in the form of classes and methods to link them to the graphical user interface template using PyQt. The analysis requirements, design, and implementation of user graphic interface were explained. The graphical user interface permitted conducted two experiments using the PBI technique and analyzing their differences and similarities, and demonstrating that the algorithm for reconstruction was testing successfully.

Keywords: Beamline, graphical user interface, image processing, python, tomography

Resumen: *Esta investigación consistió en desarrollar una interfaz gráfica de usuario en lenguaje Python para la reconstrucción de imágenes basada en la técnica de propagación basada en imágenes (PBI). La metodología utilizada consistió en volver a escribir y ordenar el código existente reformulándolo en forma de clases y métodos para vincularlo a la plantilla de interfaz gráfica de usuario mediante PyQt. Se explicaron los requisitos de análisis, el diseño y la implementación de la interfaz gráfica del usuario. La prueba de la interfaz gráfica se realizó en dos experimentos utilizando la técnica PBI, analizando sus diferencias y similitudes, lo que demuestra que la interfaz gráfica de usuario, su herramienta, y el algoritmo para la reconstrucción fueron probados con éxito.*

Palabras clave: *Interfaz gráfica de usuario, línea de luz, procesamiento de imágenes, python, tomografía*

1 Introduction

Micro computed tomography (micro-CT) is a non-destructive technique tool which obtains tri-dimensional images of the sum of bi-dimensional images or slices from a sample (Boerckel *et al.*, 2014). The principle of micro-CT

is based on the attenuation of x-rays passing through the object or sample being imaged. As an x-ray passes through the tissue, the intensity of the incident X-ray beam is diminished according to the equation, $I_x = I_0 e^{-\mu x}$, where I_0 is the intensity of the incident beam, x is the distance from the source, I_x is the intensity of the beam at distance x from the

source, and μ is the linear attenuation coefficient (Stauber & Müller, 2008).

Conventionally computed tomography (CT) uses the absorption contrast which does not permit some details to be seen in some type of samples due to weak absorption, but phase shifts in the X-ray beam can be applied for obtaining the best image (Bronnikov, 2006a). A significant improvement over conventional attenuation-based X-ray imaging, which lacks contrast in small objects and soft biological tissues, is obtained by introducing phase-contrast imaging (Zhou & Brahme, 2008). The inline phase-contrast X-ray imaging method, sometimes also called the image-based propagation technique (PBI) or the in-line holography process, exploits the Fresnel diffraction and is dubbed the phase-contrast imaging method in microtomography, which is made possible by using third generation synchrotron radiation sources or microfocus X-ray tubes (Bronnikov, 2006a) (Zhou & Brahme, 2008). Absorption-contrast X-ray imaging serves to visualize the variation in its attenuation within the volume of a given sample, whereas phase contrast allows one to visualize variations in the X-ray refractive index (Gureyev *et al.*, 2009).

In the principle of in-line phase-contrast imaging, the projected images of the computer phantom of the spheres are shown for different positions of the detector along the z-axis. If the phase contrast occurs in the Fresnel diffraction region, it means that it is necessary to place the detector at a certain distance from the source (Bronnikov, 2006a).

The image is edge-enhanced, and for soft tissues, it is possible to retrieve the phase projection from a single in-line image. The phase contrast technique is used for reconstructing the phase coefficient using the retrieved phase projections (Cai, 2009). In the PBI phase of contrast X-ray imaging, the phase contrast effects are due to thick samples, where the contrast effect increases linearly with the sample according to detector distance (Lussani *et al.*, 2015): High-resolution X-ray produces detailed three-dimensional images of soft tissue and bone structure. In the case of soft tissue, the highest resolutions are achieved with the help of a contrast agent, which increases the X-ray attenuation of the tissue of interest. For this technique, the need for high X-ray doses to obtain the finest resolution precludes scanning of live specimens (Phenogenomics, 2019). The multi-contrast X-ray images of a mouse can be obtained with a conventional X-ray image based on attenuation, the differential phase-contrast image based on X-ray

refraction, and dark-field image based on X-ray scattering (Bech *et al.*, 2013).

The reconstruction process transforms the raw acquisition data into a stack of 2D cross-sections through the sample, resulting in a 3D data set. A number of artifact and noise reduction algorithms are integrated to reduce ring artifacts, beam hardening artifacts, COR (center of rotation) misalignment, detector or stage tilt, pixel non-linearities, among others (Zhao *et al.*, 2009).

Phase retrieval is a method permitted the quantitative analysis of images, reconstructing the image phase from the measured intensity of projections, in-line phase-contrast X-ray imaging provides characteristics of images in absorption and refraction (Chen *et al.*, 2013).

Phase retrieval enables us to obtain quantitative information about the sample from phase-contrast images (Mayo *et al.*, 2003a). Microtomography experiments can be performed in the so-called Propagation Based Imaging (PBI) modality by using a sufficiently coherent X-ray beam, such as the one obtained at e.g. third generation synchrotron then, both the amplitude and phase transmitted through the sample can be retrieved from the radiography a quantitative relationship exists between the phase shift induced by the object and the recorded intensity. The inversion of this relationship is called phase retrieval and in PBI this can be performed via digital image processing (Bronnikov, 2006a). Propagation-based imaging requires that the detector is positioned at a sufficient distance from the sample; optical elements are unnecessary between the sample and the detector.

Python is a high-level general purpose programming language because code is automatically compiled to byte code and executed. Python is suitable for use as a scripting language, web application implementation language, etc. Python can be extended in C and C++, and can provide the speed needed for even computer intensive tasks, because of its strong structuring constructs (nested code blocks, functions, classes, modules, and packages) and its consistent use of objects and object-oriented programming (Kuhlman, 2009).

Python has a huge number of Graphical User Interface (GUI) frameworks (or toolkits) available for it, the major cross-platform technologies upon which Python frameworks are based include Gtk, Qt, Tk and wxWidgets, although many other technologies provide actively maintained Python bindings (Simon, 2019). PyQt a Python graphic

tool, brings together the Qt C++ cross-platform application framework and the cross-platform interpreted by the Python language. PyQt is a set of Python v2 and v3 multiplatform bindings (Riverbank, 2019).

Python is being widely used to create scripts which cover different necessities in computational scenarios. For example, the Brazilian Synchrotron Light Laboratory successfully developed Python scripts to control beamlines operations, including a case of GUI creation using Tkinter (Beniz & Espindola, 2016).

Python, Qt and some Python libraries: PyQt, PyDM and Py4syn are powerful resources of these modules and Python straightforward coding guarantees flexible user interfaces: it is possible to combine graphical applications with intelligent control procedures (Fedel *et al.*, 2017).

Py4Syn, an open-source Python-based library for data acquisition, device manipulation, scan routines and other helper functions which is driven by easy-to-use and scalability ideals, offers control system agnostic solutions and high customization levels for scans and data output, covering distinct techniques and facilities for synchrotrons (Slepicka *et al.*, 2015).

2 Methodology

2.1 Biomedical Beamline for *in vivo* and *in-vitro* experiments

The biomedical beamline, part of the European Synchrotron Radiation Facility (ESRF), located in Grenoble (France), is involved both in diagnostic imaging and therapeutic irradiation for pre-clinical and potentially clinical applications (ESRF, 2019a). In the scan process the object is moved vertically through the beam while the detector type Charge-Couple Device (CCD) camera constantly acquires projection images (Donzelli *et al.*, 2016).

The wiggler in biomedical beamline is a neat way to increase the intensity of synchrotron radiation. It is a periodic arrangement of dipole magnets generating an alternating static magnetic field which deflects the electron beam sinusoidally. The filters are also placed as beam attenuators. They are located between the source and the sample to avoid overheating of the optical elements in the optic hutch (ESRF, 2019b).

2.2 Phantom

The routine preclinical CT calibration phantom (Price *et al.*, 1990) consists of known tissue-mimicking material (King *et al.*, 2011) that are ideally suited for preclinical CT number calibration or for further multiple energy research when using a dedicated image-guided microirradiators (micro-IR) or preclinical *in vivo* cone-beam CT devices. This routine phantom consists of a validation and calibration phantom as an independent test to determine and assess the accuracy and precision of dual energy computed tomography (DE-CT) material decomposition algorithms (Solutions, 2019a).

2.3 Microtomography Technique

Figure 1 shows the phantom placed on the CT stage during the acquisition, the distance between the detector and the stage was 2.5 m.

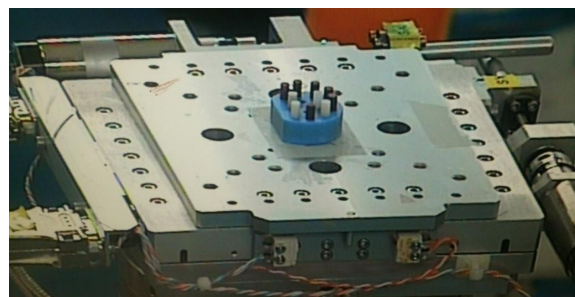


Figure 1: Phantom placed on the Computed Tomographic stage during the acquisition.

After preparing and aligning the sample stage, two wigglers were set: W 150:55 mm and W 125:65 mm, for each selected energy at 30 keV, two filters (0.8 C + 0.5 Al) were manually introduced to keep the same incoming flux on the object and to reduce the heat load on the optical elements.

2.4 Software Development

A Graphic User Interface was developed in Python Language for beamline in ESRF (Grenoble – France). It was designed for online image reconstruction during experiments. Autonomous handling of reconstruction software and the specific routines were developed for the specific users. The first step was to structure the present code into different classes and methods, the second step involved the PyQt library for construction

the GUI. The main goal of the GUI is to provide a user-friendly multi-technique platform that can be used to handle the data obtained from Propagation-based imaging (PBI) technique.

The program template was linked to the functions grouped into classes in the python code, according to the python code made by scientists of beamline. The template generates a text file, according to the instruction manual.

The tab "Range Parameters" contains the COR RANGE parameter which refers to the center of rotation, this parameter allows linking to the script to reconstruct a single slice of the volume concerned using different centers of rotation in the range generated automatically from reconstruction software. The CT files are saved in the COR folder (see figure 7). The delta-beta range parameter allows linking to the script to reconstruct a single slice of the volume concerned using a different Paganin number in the range (2480-2550). The CT files are saved in the PAG folder. The folder is created automatically (see figure 7).

The GUI allows the following operations: The "Save Parameters" button writes the expert parameters and basic parameters used for reconstruction in a text file. The "Load Parameters" button updates the expert and basic parameters reconstruction from a text file.

For the development of the GUI the Cascade Model is used, the same one that is used for the development of the application, the development steps are seen downwards (one after the other, in a linear and sequential way); this model is used in the development of applications whose approach considers development times of applications, small or standard systems, cost is a factor that is not considered, and backsliding to the previous phases is not accepted. The phases of the model are: Requirement Analysis, Design, Development and Implementation, Testing and Release (Maintenance) (Pressman, 2010).

2.4.1 Tool for reconstruction and Algorithms

PyHST2 is a tool for reconstruction based on Python language which implements parallel geometry for phasecontrast and absorption tomography; the code implements besides a default filtered back projection reconstruction algorithm (Bronnikov, 2006b), iterative reconstruction techniques with a-priori knowledge to improve the reconstruction quality or reduce the required data volume and reach a given quality goal.

The acquired images were reconstructed using the filtered-back projection algorithm after the application of the single defocused-image Paganin algorithm (Mirone *et al.*, 2013).

2.4.2 Requirements Analysis

The purpose of the needs analysis is to examine the feasibility and importance of the functions. The results of this phase are the specifications that contain the requirements that must be developed; thus, the following requirements were determined: implement a graphical interface that allows the entry of parameters for image reconstruction, upload data to the interface through an external file, provide an easy-to-use interface, and multitechnical platform that allows the management of the instrumentation for the acquisition of images.

2.4.3 GUI Design

The components of this phase use the diagrams that show the behavior of the system, the instructions on the architecture of the GUI and the applied technologies which are also adjusted, such as: programming languages, use of libraries or libraries, programming techniques and structures of control. So, based on the requirements we have designed some diagrams that describe its operation, behavior, elements, actors, etc. (see figures 2 to 4).

a) System modeling

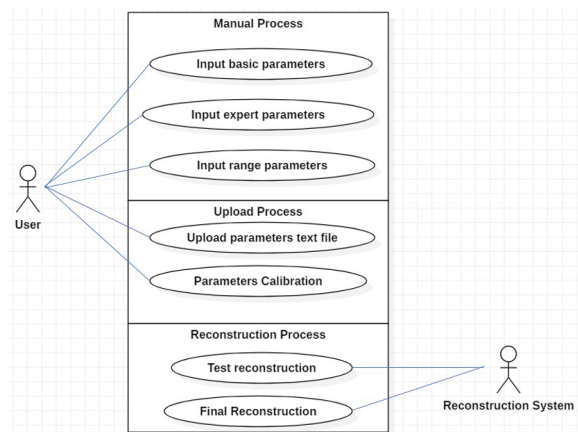


Figure 2: Use Case of Graphical User Interface.

b) Coding Structure

The image reconstruction code was structured into classes and methods for its call from the GUI using

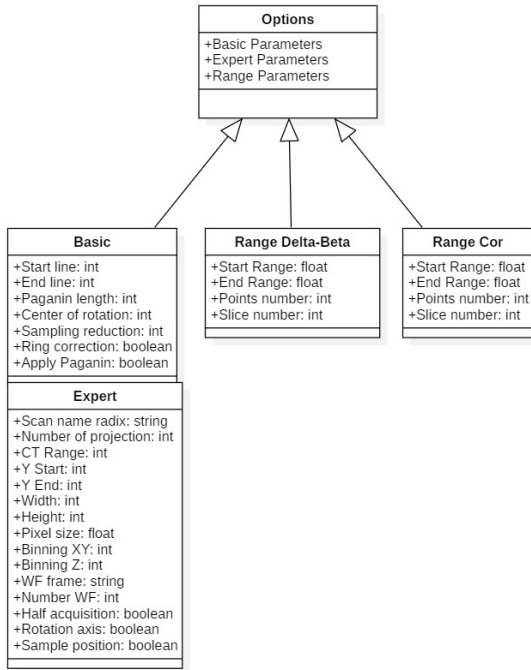


Figure 3: Class Diagram of Graphical User Interface

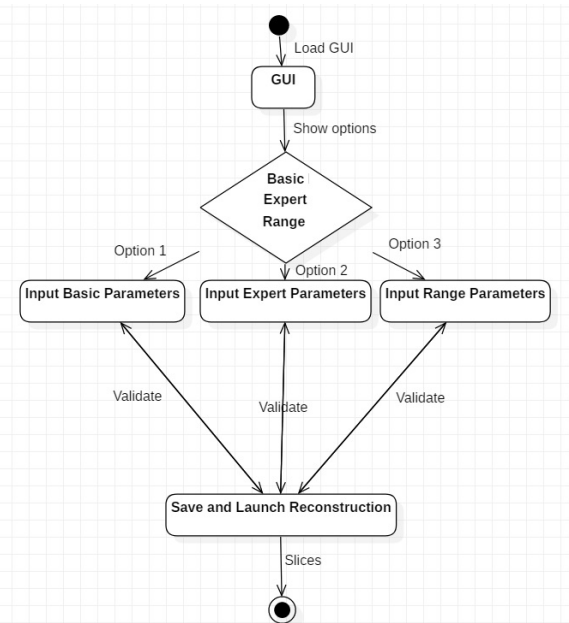


Figure 4: Estate Diagram of Graphical User Interface

the PyQt tools for the construction of the GUI (see table 1.).

2.4.4 Implementation

The figures 5 and 6 show a part of the structure of programming code for the calibration of the Paganin length.

```

9 from PyQt4 import QtCore, QtGui
10
11 try:
12     _fromUtf8 = QtCore.QString.fromUtf8
13 except AttributeError:
14     def _fromUtf8(s):
15         return s
16
17 try:
18     _encoding = QtGui.QApplication.UnicodeUTF8
19     def _translate(context, text, disambig):
20         return QtGui.QApplication.translate(context, text, disambig, _encoding)
21 except AttributeError:
22     def _translate(context, text, disambig):
23         return QtGui.QApplication.translate(context, text, disambig)
24
25 class Ui_RangePag(object):
26     def setupUi(self, RangePag):
27         RangePag.setObjectName(_fromUtf8("RangePag"))
28         RangePag.resize(438, 294)
29         self.pushButton_51 = QtGui.QPushButton(RangePag)
30         self.pushButton_51.setGeometry(QtCore.QRect(240, 210, 93, 28))
31         self.pushButton_51.setObjectName(_fromUtf8("pushButton_51"))
32         self.label_2 = QtGui.QLabel(RangePag)
33         self.label_2.setGeometry(QtCore.QRect(82, 101, 80, 21))
34         font = QtGui.QFont()
35         font.setPointSize(10)
36         self.label_2.setFont(font)
37         self.label_2.setObjectName(_fromUtf8("label_2"))
38         self.label_3 = QtGui.QLabel(RangePag)
39         self.label_3.setGeometry(QtCore.QRect(82, 130, 127, 21))
40         font = QtGui.QFont()
41         font.setPointSize(10)
42         self.label_3.setFont(font)
43         self.label_3.setObjectName(_fromUtf8("label_3"))
44         self.lineEdit_56 = QtGui.QLineEdit(RangePag)
45         self.lineEdit_56.setGeometry(QtCore.QRect(216, 130, 137, 22))
46         self.lineEdit_56.setObjectName(_fromUtf8("lineEdit_56"))
47         self.label = QtGui.QLabel(RangePag)
48         self.label.setGeometry(QtCore.QRect(82, 72, 88, 21))
49         font = QtGui.QFont()
50         font.setPointSize(10)
51         self.label.setFont(font)
52         self.label.setObjectName(_fromUtf8("label"))

```

Figure 5: Part 1 - Coding for Range of Paganin.

```

53         self.lineEdit_55 = QtGui.QLineEdit(RangePag)
54         self.lineEdit_55.setGeometry(QtCore.QRect(216, 101, 137, 22))
55         self.lineEdit_55.setObjectName(_fromUtf8("lineEdit_55"))
56         self.lineEdit_54 = QtGui.QLineEdit(RangePag)
57         self.lineEdit_54.setGeometry(QtCore.QRect(216, 72, 137, 22))
58         self.lineEdit_54.setObjectName(_fromUtf8("lineEdit_54"))
59         self.label_4 = QtGui.QLabel(RangePag)
60         self.label_4.setGeometry(QtCore.QRect(82, 159, 105, 21))
61         font = QtGui.QFont()
62         font.setPointSize(10)
63         self.label_4.setFont(font)
64         self.label_4.setObjectName(_fromUtf8("label_4"))
65         self.lineEdit_57 = QtGui.QLineEdit(RangePag)
66         self.lineEdit_57.setGeometry(QtCore.QRect(216, 159, 137, 22))
67         self.lineEdit_57.setObjectName(_fromUtf8("lineEdit_57"))
68
69         self.retranslateUi(RangePag)
70         QtCore.QMetaObject.connectSlotsByName(RangePag)
71
72     def retranslateUi(self, RangePag):
73         RangePag.setWindowTitle(_translate("RangePag", "RangePag", None))
74         self.pushButton_51.setText(_translate("RangePag", "OK", None))
75         self.label_2.setText(_translate("RangePag", "End Range", None))
76         self.label_3.setText(_translate("RangePag", "Number of Points", None))
77         self.label.setText(_translate("RangePag", "Start Range", None))
78         self.label_4.setText(_translate("RangePag", "Slices Number", None))
79
80
81 if __name__ == "__main__":
82     import sys
83     app = QtGui.QApplication(sys.argv)
84     RangePag = QtGui.QRangePag()
85     ui = Ui_RangePag()
86     RangePag.show()
87     sys.exit(app.exec_())

```

Figure 6: Part 2 - Coding for Range of Paganin

2.4.5 Parameters GUI

The basic parameters are explained according to figure 4:

Table 1: Code Structure of Graphical User Interface.

Classes / Methods / Libraries	Description
Library: PyQt4	Set of Python bindings for Qt cross-platform.
Class 1: Calculation	Calc center of rotation.
Method 1.1: CalcCenterOfRotation	Calculate center of rotation.
Method 1.2: DoSino	Create sinograms
Method 1.3: normalization	Make the normalization of projections
Class 2: Parameters	Read text file and store the values into a dictionary
Method 2.1: addParameters	Creation parameters for reconstruction
Method 2.2: DoParFile	Create text file containing the info about the scan
Class 3: Utility	Reconstruction send to the cluster.
Method 3.1: DoScript	The reconstruction is submitted to the cluster.
Class 4: Ui.RangeCor	Create GUI for calibrate center of rotation
Method 4.1: setupUi	Create template for RangeCor
Method 4.2: retranslateUi	Calls for the RangeCor class occur.
Class 5: Ui.RangePag	Create the GUI for calibrate the Paganin legh
Method 5.1: setupUi	Create template for RangePag
Method 5.2: retranslateUi	Calls for the RangePag class occur.
Class 6: Ui.Basic_Expert	Create the GUI for calibrate the Basic_Expert
Method 6.1: setupUi	Create template for Basic_Expert
Method 6.2: retranslateUi	Calls for the Basic_Expert class occur.

- Reconstruction starts in line: indicates the starts in line of reconstruction
- Reconstruction ends in line: indicates the end in line of reconstruction
- Paganin Length: refers to Paganin dimension which input previous reconstruction
- Center of rotation: defines rotation center of reconstruction
- Sampling Reduction (SR), is a practical algorithm based on Random Sampling Reduction (RSR) (Buchmann & Ludwig, 2003).
- Ring Correction (yes/no): refers to PyHST ring correction
- Apply Paganin (yes/no)?: refers to Paganin algorithm

The expert parameters are explained according to figure 5:

- Scan Name radix: corresponds to the radix name of the file without extension.
- Number of projections: corresponds to the effective number of projections acquired
- CT Range (180/360): refers to scan at 180 or 360 degrees
- y start: region of interest (ROI) start
- y end: region of interest (ROI) end
- Width: pixels image width
- Height: pixels image height
- Pixel Size: refers to effective pixel size
- Binning XY: binning in the reconstruction plane (Mohammadi *et al.*, 2014).
- Binning Z: binning along the vertical axis
- WF name: name of one white field file
- Number of WF in the file: number of white fields acquired
- Half Acquisition (yes/no)?: refers to half acquisition
- Sample Positioning (left/right): left in the case of half acquisition

- Rotation Axis (H/V): H= horizontal and V= vertical rotation axes.

3 Results and Discussion

3.1 Software Test

The first operation into the reconstruction process was to determine the exact centre of rotation for each dataset. For this purpose, the GUI was used, and a series of reconstructions performed automatically using different centres of rotation. As a second step, the optimal ratio $\delta\beta$ (Mayo *et al.*, 2003b) to perform the phase-retrieval was chosen again using another automatic method present in the reconstruction software (see figure 3).

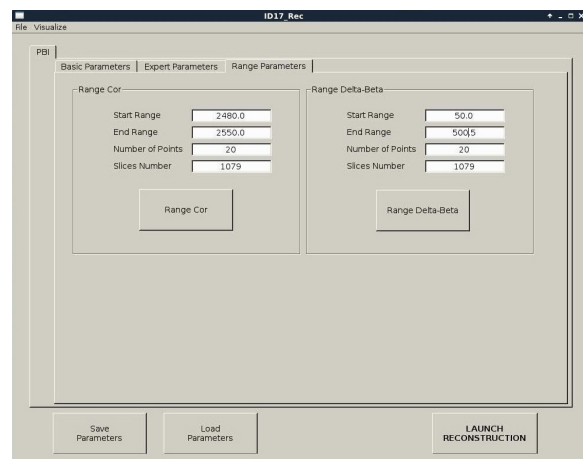


Figure 7: Range Parameters. Rotation Center and $\delta\beta$ of slice.

Figure 8 shows the basic parameters of the previous reconstruction, which would be fixed after finding the correct values in the range parameters. The expert parameters were loaded automatically from a text file generated after the micro-CT procedure (see figure 9).

3.2 Scanning of Phantom

Figure 10 illustrates a reconstructed slice at a photon energy equal to 30 keV where the regions of interest (ROI) are numbered for each material according to table 2.

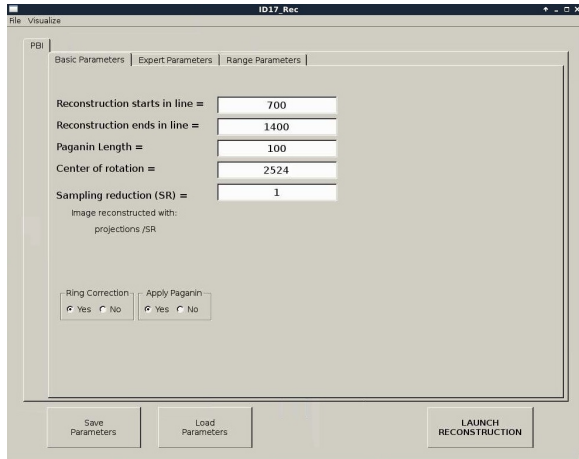


Figure 8: Basic Parameters of Slice.

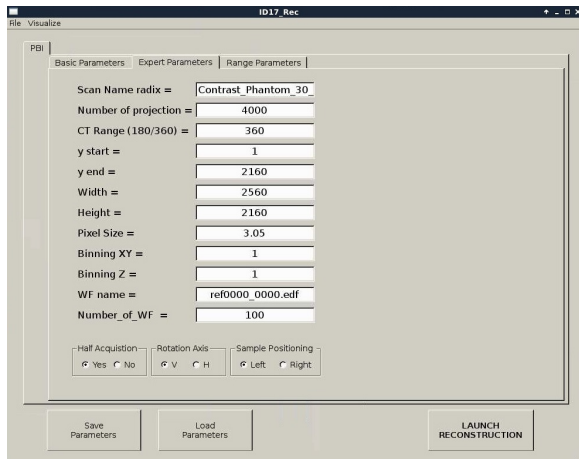


Figure 9: Experts Parameters of Slice.

Table 2: Materials of Phantom.

ROI	Material
1	Liver
2	Cortical bone (SB3)
3	Cortical bone CB2-50%
4	Bone (B200)
5	Air
6	Air
7	Breast
8	Inner bone
9	Brain
10	Cortical bone CB2-30%
11	Solid Water
12	Adipose

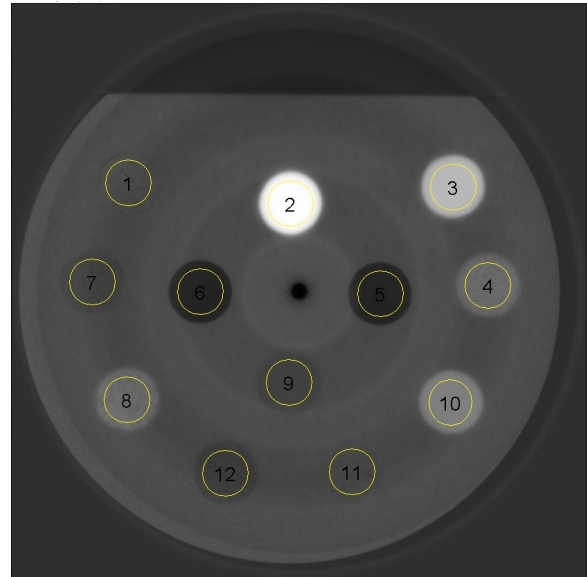


Figure 10: Slice reconstructed. Depiction of CT calibration phantom μ CT scan at 30 KeV.

3.3 Scanning of rat sample/specimen

The PlastiRat is an extremely useful tool for conducting imaging quality assurance tests as well as for irradiation planning studies, and for educational purposes. The benefit of PlastiRat is that it is biologically inert, being a motionless rigid object that represents the true anatomy of a living rat including all the mineralized components of the bones (see figure 11) (Solutions, 2019b).

Parameters of experiment:

- The distance between the sample stage and the detector was 11 m.
- Wiggler: W150 - 55 mm, W125 - 45 mm.
- Filter: 2.5 mm Al + 0.8 mm C.
- Energy: 60 KeV.
- FReLoN CCD camera coupled with 1:3.6 optic.
- Effective pixel size $47 \mu\text{m}^2$.

Parameters of reconstruction:

Sampling_reduction = 1
 Width = 2048
 COR = 180
 CT_Range = 360
 Number_of_projections = 4000
 Sample_Positioning = 1
 Rotation_Axis = 1
 End_Range = 181.0



Figure 11: Rat on the computed tomography stage.

```
Scan_Name = plastified_rat_001_
Number_of_WF = 100
y_end = 211
Only_CT = 1
y_start = 1
Paganin_Length = 50
Slices_Number = 105
Slices_NumberP = 105
Number_of_Points = 2
Reconstruction_starts = 1
Reconstruction_ends = 211
Half_Acquisition = 1
Do_Paganin = 1
Number_of_PointsP = 20
AngleCT = 0.09
```

```
DEFINE = RETRIEVAL
BinningXY = 1
Start_Range = 179.0
Pixel_Size = 2.95
End_RangeP = 65.0
WF_name = ref0000_0000.edf
Make_Sinos = 0
BinningZ = 1
Height = 211
Ring_Correction = 1
Start_RangeP = 35.0
```

3D Rendering and Segmentation:

ImageJ was used for 3D rendering and segmentation. The segmentation assigns a label to each pixel of the image describing which region or material it belongs to (Konrad-Zuse-Zentrum, 2019). Figure 12 shows the external tissue, figures 13-14 depict the skeleton view, and figures 15-16 illustrate some different views of the 3D brain of a rat using the technique region growing segmentation (Jarek, 2019).



Figure 12: Rat tissue.



Figure 13: Rat Skeleton - top view.

3.4 Comparison of results

The reconstruction parameters entered in the GUI were adequate in both experiments, allowing the 2D reconstruction to be optimized in both experiments free of image artifacts. The 3D rendering for the reconstruction of the plasticized rat, permitted to verify the accuracy of the parameters entered in the GUI, for reconstruction of each slice based on the PyHST2 tool. It was possible to segment the

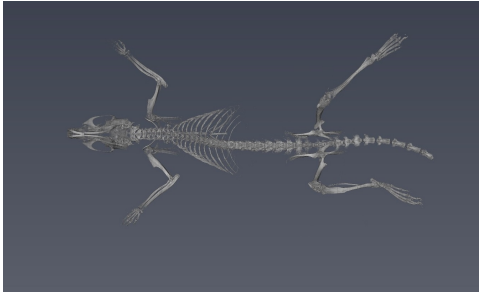


Figure 14: Rat Skeleton - bottom view.

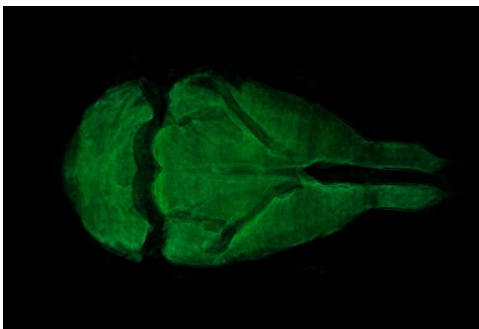


Figure 15: Rat brain - top view.

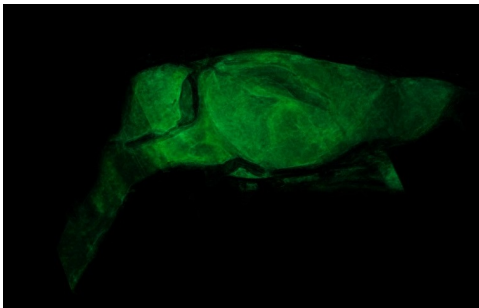


Figure 16: Rat brain - side view

external tissue, the bone structure and an internal organ (brain) of the plasticized rat. The scan of the plasticized rat and its subsequent rendering in 3D was the most complete test of the system, where the accuracy of the parameters entered into the GUI was evaluated, the use of PyHST2 as a reconstruction tool for each slice. A single data set of 700 slices was used for phantom reconstruction; instead, the plasticized rat, was used 54 data sets with 1400 slices each one for reconstruction. Another important factor is the Paganin value which is minor for the rat scan with respect to the phantom parameter allowing us to obtain a better contrast in the rat tissue and other small details. The binning values were 16 for the phantom scan and 1 for the rat scan, with the greater binning permitting an

improvement in the contrast sensitivity and signal improvements.

4 Conclusions

It can be concluded that the methods and techniques used that allowed the development of this graphic interface were carried out successfully. The reconstruction parameters entered in the graphic interface using the image-based propagation technique were successfully tested in two experiments, which was demonstrated in the 2D and 3D reconstructions.

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